APPLICATION NOTE: TWO-QUADRANTS PRINCIPLE







Two-quadrants operation (2QO) aka source-sink principle



Visualisation of voltage at switchover of source to sink (example: motor)



(A) Voltage of the E.U.T while the source is active

(B) Point of switching the source off -> the motor breaks and starts to generate excessive energy.

(C) Voltage peak of regeneration before the sink (electronic load) kicks in. Transient time: < 10 ms, typical 5 ms

(D) Point of powering the motor again -> it accelerates

(E) Voltage drops for a short moment, until compensated by the source (transient time: <2 ms)



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Voltage and current progression over time (example with battery)



(1) Voltage setting of source (power supply) for charging the battery (e.g. 27 V). The source charges the battery with a constant current until the max. voltage is reached and the current is almost zero.

(2) Battery & charging voltage. At the start, the battery has normal charge. During discharge phase the voltage can go down to the any given level.

(3) Voltage setting of sink (electronic load), as defined by the power supply via Share bus and thus identical to (1). It is used to discharge the battery to a certain level, e.g. 20 V

(4) Charging current

(5) Discharging current

Equipment

There is basically one question: What devices to buy for a 2QO system? Two options: either a bidirectional supply or a combination of a power supply and an electronic load. Both have advantages and disadvantages.

Combination of power supply & electronic load:

- + Seperate units, which can also be used for other purposes in different locations
- + Extendable
- + Source and sink power can be matched by selecting the proper models
- More expensive

Bidirectional supply

- + More cost effective, because less components
- Less power
- Sink power usually lower than source power
- More complicated construction, more susceptible to defects



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Example wiring for 2QO with ELR 9000 and PSI 9000, each as two unit master-slave system





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